

## Situational awareness & assistance

### Multidirectional video feed

Source	Navcams (visual sensor)
Number	5
Video	VGA (640 x 480 pixels)
Horizontal field of view	100 degrees
Availability	One navcam at a time

### Object & range detection

Sensor	Ultrasonic
Number	5
Range	Up to 6 m (20 ft)
Feedback	Audio and visual object warning

## Operational safety

### Shrouding

Material	Carbon fibre
Function	Defines propeller rotation area Protects from damage at low speed

### Signalisation lights

Navigation lights	2 green on the right, 2 red on the left
Anti-collision lights	1 top strobe, 1 bottom strobe

### Ground proximity detection

Avoidance procedure	Automatic stop (can be deactivated)
Warning signals	Audio & visual

### Flight assistance features (Interactive mode)

Cruise control	Maintains (low) constant speed in a given direction
Distance lock	Keeps distance to frontal objects 3 - 5 m (9.8 - 16 ft)
Obstacle avoidance	Depending on flight phase

### Safety procedures

Automated failsafe behaviours	Geofencing, return home, emergency stop, emergency landing
Operator triggered	Hold position, return home, go land, land now, emergency motor cut-off

### Autopilot fallback

Type	Independent low-level autopilot (backup for main autopilot)
Manual RC control	Independent RC controller (take manual control at any time)

## Ground station software

Software application	senseFly eMotion X (supplied)
Mission planning	Intuitive 3D user interface Click and drag to set mission blocks Automatic 3D flight planning Edit mission plans during flight
Flying	Automated system checks Automated take-off & landing Real-time flight status Main camera video feed integration Thermal video feed integration Navcam video feed integration Fully automatic flight Interactive ScreenFly Manual flight (with assistance functions) In-flight switch between flight modes Black-box recording of all flight & mission parameters
After your flight	Project & data management DNG to JPEG conversion

**eXom**  
senseFly



The intelligent **mapping**  
& **inspection** drone

## Flight system

Type	V-shaped quadcopter
Dimensions (incl. shrouding)	56 x 80 x 17 cm (22 x 32 x 7 in)
Engines	4 electric brushless motors
Propellers	4
Take-off weight	1.8 kg (3.9 lb) incl. battery, payload & shrouding
Flight time (full system)	Up to 22 min
Max. climb rate	7 m/s (15 mph)
Max. airspeed	Automatic flight: 8 m/s (18 mph) Manual flight: 12 m/s (27 mph)
Wind resistance	Automatic: up to 8 m/s (18 mph) Manual: up to 10 m/s (22 mph)
Autopilot & control	IMU, magnetometer, barometer & GPS
Materials	Composite body, moulded carbon fibre arms and legs, precision-molded magnesium frame, precision-molded injected plastic
Operating temperature	-10 to 40° C (14°-104° F)

## Wireless communication

### Main communication link

Type	Digital, dual omnidirectional antennas, dual band, encrypted
Frequency	2.4 GHz & 5 GHz ISM bands (country dependent)
Data transmitted	Commands, main camera stream, navcam stream, sensor data, etc.
Range	Up to 2 km (1.2 mi)

### RC (Remote control)

Type	Digital
Frequency	2.4 GHz
Range	Up to 800 m (0.5 mi)

## System power

Technology	Smart battery
Type	LiPo, 3 cell, 8500 mAh
Power level display	LED display on battery, on-screen information
Charging time	1 - 1.5 h

## Integrated payloads

### TripleView head

#### Main camera

Still images	38 MP, mechanical shutter DNG (RAW image with correction metadata) Ground sampling distance (GSD): Down to 1 mm/pixel* (at 6 m) Recorded on board Geo-referenced (position & orientation)
Video	HD (1280 x 720 pixels) Recorded on board or streamed
Horizontal field of view	63 degrees
Digital zoom	6x

#### Thermal camera

Still images/video	Thermal (80 x 60 pixels) overlaid on main camera stream
Horizontal field of view	50 degrees
Edge enhancement	Yes

### Head navcam (visual sensor)

Video	VGA (640 x 480 pixels)
Video live streaming range	Up to 2 km (1.24 miles)
Horizontal field of view	100 degrees

### Lights

Headlamp	Yes, used for video
Flash	Yes (not active upon release)

### Additional navcams (visual sensors)

Number	4 navcams
Positions	Left, right, rear, bottom
Video	VGA (640 x 480 pixels)
Horizontal field of view	100 degrees
Availability	One navcam at a time
Operational use	Side views (w/o turning main camera) & parallel flight along objects Back-up safely & control in tight environments Landing & ground proximity

\*Depends upon environmental conditions (light, wind, surface type)

## Flight modes

Types	Automatic Interactive ScreenFly Manual (RC)
Availability	Switch between modes at any time

### Automatic

Control interface	Mouse, keyboard or touchscreen
Mission planning	Drag-and-drop mission blocks
Types of mission blocks	Horizontal mapping Around point of interest User-defined route
In-flight mission changes	Yes: manual waypoint changes and updates possible at any time

### Interactive ScreenFly

Primary control interface	Screen-based actions & USB joypad
Flight assistance (depending on the flight phase)	Cruise control Distance lock Obstacle avoidance

### Manual (RC)

Primary control interface	RC (remote control)
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## On-board computing

Type	4 on-board CPUs
Quad-core processor	Principal autopilot & artificial intelligence
Dual-core processor	Video co-processing
Single-core processor	Low-level autopilot (safety fallback) and motor control
Single-core processor	Communication link management

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